

# The difference between the weak and the strong core from the design point of view

#### Ville Korpela, Michele Lombardi and Foivos Savva

Department of Economics, University of Southampton

November 3, 2022

**ASSET Conference 2022** 





# Mechanism design vs implementation



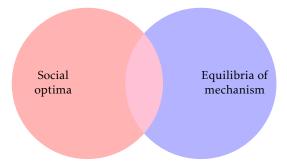
# Mechanism design vs implementation

• Usually, the existence of a desirable (socially optimal) equilibrium is sufficient.



# Mechanism design vs implementation

- Usually, the existence of a desirable (socially optimal) equilibrium is sufficient.
- (Full) implementation: All equilibria are socially optimal **and** each social optimum can be realized through some equilibrium.





# Implementation via mechanisms vs implementation via rights structures

Mechanisms	<b>Rights structures</b>		
Strategies	Rights		
Noncooperative equilibrium notions	Cooperative equilibrium notions		



#### Mechanisms and rights structures, example

Primitives			
$N = \{1, 2\}, \mathcal{R} = \{R, R'\}$			
$\phi(R) = \{x, w\}, \ \phi(R') = \{x\}$			

$R_1$	$R_2$	$R'_1$	$  R'_2$
x	w	x	w
Z	z	z	x
w	x	y	z
у	y y	w	y y

Table: Preferences



Table: Mechanism/game form

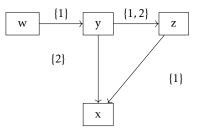
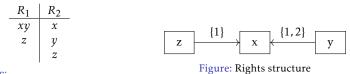


Figure: Rights structure



#### To cooperate or not?



#### Figure: Preferences

- Weak core:  $C(\Gamma, R) = \{x, y\}.$
- Strong core:  $SC(\Gamma, R) = \{x\}.$

Introduction	Environment	Results	Applications	Conclusion	Supplementary material		
0000●0	00	00000	0000	OO	O		
This paper							



• What SCRs can we implement in weak core?



• What SCRs can we implement in weak core?

• What SCRs can we implement is strong core?



• What SCRs can we implement in weak core?

• What SCRs can we implement is strong core?

• Remarks and applications.

Environment 00 Results 00000 Application: 0000 Conclusion 00 Supplementary material O

#### **Related literature**

Noncooperative mechanisms

Maskin (1999) RES Moore and Repullo (1990) JET Jackson (1991) ECMA Dutta and Sen (2012) GEB De Clippel (2014) AER

Environment OO Results 00000 Applications

Conclusion 00 Supplementary material O

# Related literature

Noncooperative mechanisms

Maskin (1999) RES Moore and Repullo (1990) JET Jackson (1991) ECMA Dutta and Sen (2012) GEB De Clippel (2014) AER

#### **Rights structures**

Koray and Yildiz (2018) JET Korpela et al (2020) JET Korpela et al (2021) GEB Savva (2021) EL Lombardi et al (2021)



Set of agents N = {1, 2, ..., n}, set of all coalitions N and set of all non-empty coalitions N<sub>0</sub>.



- Set of agents *N* = {1, 2, ..., *n*}, set of all coalitions *N* and set of all non-empty coalitions *N*<sub>0</sub>.
- Set of social outcomes *X*.



- Set of agents *N* = {1, 2, ..., *n*}, set of all coalitions *N* and set of all non-empty coalitions *N*<sub>0</sub>.
- Set of social outcomes *X*.
- Each  $i \in N$  has a preference relation on  $X, R_i \in \mathcal{R}_i$ .



- Set of agents *N* = {1, 2, ..., *n*}, set of all coalitions *N* and set of all non-empty coalitions *N*<sub>0</sub>.
- Set of social outcomes *X*.
- Each  $i \in N$  has a preference relation on  $X, R_i \in \mathcal{R}_i$ .
- $(R_1, ..., R_n) \in \mathcal{R}$  is called a preference profile.



- Set of agents N = {1, 2, ..., n}, set of all coalitions N and set of all non-empty coalitions N<sub>0</sub>.
- Set of social outcomes *X*.
- Each  $i \in N$  has a preference relation on  $X, R_i \in \mathcal{R}_i$ .
- $(R_1, ..., R_n) \in \mathcal{R}$  is called a preference profile.
- Social choice rule  $\phi : \mathcal{R} \rightrightarrows X$ , where for all  $R \in \mathcal{R}$ ,  $\emptyset \neq \phi(R) \subseteq X$ .



- Set of agents *N* = {1, 2, ..., *n*}, set of all coalitions *N* and set of all non-empty coalitions *N*<sub>0</sub>.
- Set of social outcomes *X*.
- Each  $i \in N$  has a preference relation on  $X, R_i \in \mathcal{R}_i$ .
- $(R_1, ..., R_n) \in \mathcal{R}$  is called a preference profile.
- Social choice rule  $\phi : \mathcal{R} \rightrightarrows X$ , where for all  $R \in \mathcal{R}$ ,  $\emptyset \neq \phi(R) \subseteq X$ .
- $L_i(x, R) = \{y \in X | xR_i y\}$  and  $SL_i(x, R) = \{y \in X | xP_i y\}.$



- Set of agents *N* = {1, 2, ..., *n*}, set of all coalitions *N* and set of all non-empty coalitions *N*<sub>0</sub>.
- Set of social outcomes *X*.
- Each  $i \in N$  has a preference relation on  $X, R_i \in \mathcal{R}_i$ .
- $(R_1, ..., R_n) \in \mathcal{R}$  is called a preference profile.
- Social choice rule  $\phi : \mathcal{R} \rightrightarrows X$ , where for all  $R \in \mathcal{R}$ ,  $\emptyset \neq \phi(R) \subseteq X$ .
- $L_i(x, R) = \{y \in X | xR_i y\}$  and  $SL_i(x, R) = \{y \in X | xP_i y\}.$

*Interpretation*: social planner wants to implement  $\phi$ , but knows only  $\mathcal{R}$ .

Environment O Results 00000 Applications 0000 Conclusion 00 Supplementary material O

#### **Rights structures**

#### **Object of design** for the social planner: means to implement SCR $\phi$ .

Environment O Results 00000 Applications 0000 Conclusion 00 Supplementary material O

#### **Rights structures**

**Object of design** for the social planner: means to implement SCR  $\phi$ .

Key idea: allocation of rights in the society (constitution).

 $\Gamma = (S, h, \gamma)$ , where:

Environment O• Results 00000 Applications 0000 Conclusion 00 Supplementary material O

# **Rights structures**

**Object of design** for the social planner: means to implement SCR  $\phi$ .

Key idea: allocation of rights in the society (constitution).

 $\Gamma = (S, h, \gamma)$ , where:

1. *S* is a **state space**.

Environment

Results 00000 Applications 0000 Conclusion 00 Supplementary material O

# **Rights structures**

**Object of design** for the social planner: means to implement SCR  $\phi$ .

- $\Gamma = (S, h, \gamma)$ , where:
  - 1. *S* is a **state space**.
  - 2.  $h: S \to X$  is the **outcome function**.

Environment

Results 00000 Applications 0000 Conclusion 00 Supplementary material O

# **Rights structures**

**Object of design** for the social planner: means to implement SCR  $\phi$ .

- $\Gamma = (S, h, \gamma)$ , where:
  - 1. S is a state space.
  - 2.  $h: S \to X$  is the **outcome function**.
  - 3.  $\gamma: S \times S \rightrightarrows \mathcal{N}_0$  is a codes of rights.

Environment O Results 00000 Applications 0000 Conclusion 00 Supplementary material O

# **Rights structures**

**Object of design** for the social planner: means to implement SCR  $\phi$ .

- $\Gamma = (S, h, \gamma)$ , where:
  - 1. S is a state space.
  - 2.  $h: S \to X$  is the **outcome function**.
  - 3.  $\gamma: S \times S \Rightarrow \mathcal{N}_0$  is a **codes of rights**. (If  $\gamma(s, t)$  is always a singleton, then  $\Gamma$  is called an **individual-based** rights structure.)

Environment O Results 00000 Applications 0000 Conclusion 00 Supplementary material O

# **Rights structures**

**Object of design** for the social planner: means to implement SCR  $\phi$ .

Key idea: allocation of rights in the society (constitution).

- $\Gamma = (S, h, \gamma)$ , where:
  - 1. *S* is a **state space**.
  - 2.  $h: S \to X$  is the **outcome function**.
  - 3.  $\gamma: S \times S \Rightarrow \mathcal{N}_0$  is a **codes of rights**. (If  $\gamma(s, t)$  is always a singleton, then  $\Gamma$  is called an **individual-based** rights structure.)

**Weak core**:  $s \in C(\Gamma, R)$  if for all  $t \in S$ , there is no  $K \in \gamma(s, t)$ , such that for all  $i \in K$  we have  $h(t)P_ih(s)$ .

Environment O Results 00000 Applications 0000 Conclusion 00 Supplementary material O

# **Rights structures**

**Object of design** for the social planner: means to implement SCR  $\phi$ .

Key idea: allocation of rights in the society (constitution).

- $\Gamma = (S, h, \gamma)$ , where:
  - 1. S is a state space.
  - 2.  $h: S \to X$  is the **outcome function**.
  - 3.  $\gamma: S \times S \Rightarrow \mathcal{N}_0$  is a **codes of rights**. (If  $\gamma(s, t)$  is always a singleton, then  $\Gamma$  is called an **individual-based** rights structure.)

Weak core:  $s \in C(\Gamma, R)$  if for all  $t \in S$ , there is no  $K \in \gamma(s, t)$ , such that for all  $i \in K$  we have  $h(t)P_ih(s)$ . Strong core:  $s \in SC(\Gamma, R)$  if for all  $t \in S$ , there is no  $K \in \gamma(s, t)$ , such that for all  $i \in K$  we have  $h(t)R_ih(s)$  with strict preference for at least one  $j \in K$ .

Environment O Results 00000 Applications 0000 Conclusion 00 Supplementary material O

# **Rights structures**

**Object of design** for the social planner: means to implement SCR  $\phi$ .

Key idea: allocation of rights in the society (constitution).

- $\Gamma = (S, h, \gamma)$ , where:
  - 1. S is a state space.
  - 2.  $h: S \to X$  is the **outcome function**.
  - 3.  $\gamma: S \times S \Rightarrow \mathcal{N}_0$  is a **codes of rights**. (If  $\gamma(s, t)$  is always a singleton, then  $\Gamma$  is called an **individual-based** rights structure.)

Weak core:  $s \in C(\Gamma, R)$  if for all  $t \in S$ , there is no  $K \in \gamma(s, t)$ , such that for all  $i \in K$  we have  $h(t)P_ih(s)$ . Strong core:  $s \in SC(\Gamma, R)$  if for all  $t \in S$ , there is no  $K \in \gamma(s, t)$ , such that for all  $i \in K$  we have  $h(t)R_ih(s)$  with strict preference for at least one  $j \in K$ .

Implementation:

for any  $R \in \mathcal{R}$ ,  $\phi(R) = h(C(\Gamma, R))$  (or  $= h(SC(\Gamma, R))$ ).

Introduction	Environment	Results	Applications	Conclusion	Supplementary material
000000	00	©0000	0000	OO	O



Maskin-monotonicity



#### Maskin-monotonicity

There exists  $Y \subseteq X$  with  $\phi(\mathcal{R}) \subseteq Y$ , such that for all R, R' and  $x \in \phi(R)$ :

if for all i,  $[L_i(x, R) \subseteq L_i(x, R')] \cap Y$ , then  $x \in \phi(R')$ .



#### Maskin-monotonicity

There exists  $Y \subseteq X$  with  $\phi(\mathcal{R}) \subseteq Y$ , such that for all R, R' and  $x \in \phi(R)$ :

if for all i,  $[L_i(x, R) \subseteq L_i(x, R')] \cap Y$ , then  $x \in \phi(R')$ .

Unanimity



#### Maskin-monotonicity

There exists  $Y \subseteq X$  with  $\phi(\mathcal{R}) \subseteq Y$ , such that for all  $\mathcal{R}, \mathcal{R}'$  and  $x \in \phi(\mathcal{R})$ :

if for all i,  $[L_i(x, R) \subseteq L_i(x, R')] \cap Y$ , then  $x \in \phi(R')$ .

#### Unanimity

There exists  $Y \subseteq X$  with  $\phi(\mathcal{R}) \subseteq Y$ , such that for all R and  $x \in Y$ :

if for all *i*,  $Y \subseteq L_i(x, R)$ , then  $x \in \phi(R)$ .



#### Maskin-monotonicity

There exists  $Y \subseteq X$  with  $\phi(\mathcal{R}) \subseteq Y$ , such that for all R, R' and  $x \in \phi(R)$ :

if for all i,  $[L_i(x, R) \subseteq L_i(x, R')] \cap Y$ , then  $x \in \phi(R')$ .

#### Unanimity

There exists  $Y \subseteq X$  with  $\phi(\mathcal{R}) \subseteq Y$ , such that for all R and  $x \in Y$ :

if for all *i*,  $Y \subseteq L_i(x, R)$ , then  $x \in \phi(R)$ .

#### Theorem

The following are equivalent:

- (i)  $\phi$  is implementable in weak core.
- (ii)  $\phi$  satisfies Maskin-monotonicity and unanimity.
- (iii)  $\phi$  is implementable in weak core by an individual-based rights structure.

Introduction 000000	Environment 00	Results ○●○○○	Applications 0000	Conclusion OO	Supplementary material O
Example					
$\phi(R) = \{x, w\}, \ \phi(R') = \{x\}$					
		x z w	$\begin{array}{c cccc} R_2 & R_1' & R_2' \\ w & x & w \\ z & z & x \\ x & y & z \\ y & w & y \end{array}$		
Table: Preferences					
	[	{1} {2}	x	{1}	

Figure: Rights structure

Introduction	Environment	Results	Applications	Conclusion	Supplementary material		
000000	00	00000	0000	OO	O		
Interpretation							



• When we consider implementation of a SCR in weak core, coalitions are **irrelevant**!



- When we consider implementation of a SCR in weak core, coalitions are **irrelevant**!
- Whichever SCR is implementable by rights structures in weak core, is also implementable by an *individual-based* rights structure.



- When we consider implementation of a SCR in weak core, coalitions are **irrelevant**!
- Whichever SCR is implementable by rights structures in weak core, is also implementable by an *individual-based* rights structure.
- There is no value in *coalitional rights* from the economic design point of view.

Introduction Environment Result	Conclusion	Supplementary material
000000 00 000	OO	O



A few further definitions:

$$I_K(x, R) = \bigcap_{i \in K} \{ y \in X | xI_i y \text{ for all } i \in K \}, \text{ and} \\ SL_K(x, R) = \bigcup_{i \in K} SL_i(x, R).$$



A few further definitions:

$$I_K(x, R) = \bigcap_{i \in K} \{ y \in X | xI_i y \text{ for all } i \in K \}, \text{ and} \\ SL_K(x, R) = \bigcup_{i \in K} SL_i(x, R).$$

Weak SC-monotonicity



A few further definitions:

$$I_K(x, R) = \bigcap_{i \in K} \{ y \in X | xI_i y \text{ for all } i \in K \}, \text{ and} \\ SL_K(x, R) = \bigcup_{i \in K} SL_i(x, R).$$

#### Weak SC-monotonicity

There exists  $Y \supseteq \phi(\mathcal{R})$  such that for all R, R' and  $x \in \phi(R)$ :

if for all K,  $[I_K(x, R) \bigcup SL_K(x, R)] \cap Y \subseteq I_K(x, R') \bigcup SL_K(x, R')$ , then  $x \in \phi(R')$ .



A few further definitions:

$$I_K(x, R) = \bigcap_{i \in K} \{ y \in X | xI_i y \text{ for all } i \in K \}, \text{ and} \\ SL_K(x, R) = \bigcup_{i \in K} SL_i(x, R).$$

#### Weak SC-monotonicity

There exists  $Y \supseteq \phi(\mathcal{R})$  such that for all R, R' and  $x \in \phi(R)$ :

if for all K,  $[I_K(x, R) \bigcup SL_K(x, R)] \cap Y \subseteq I_K(x, R') \bigcup SL_K(x, R')$ , then  $x \in \phi(R')$ .

#### Theorem

The following are equivalent:

- (i) An SCR  $\phi$  is implementable in strong core.
- (ii) An SCR  $\phi$  satisfies weak SC-monotonicity and unanimity with respect to Y.

Introduction	Environment	Results	Applications	Conclusion	Supplementary material
000000	00	00000	0000	OO	O
		Inte	rpretation		



• Strong core ⊆ weak core. Does this mean that if a SCR is implementable in strong core it is also implementable in weak core?



- Strong core ⊆ weak core. Does this mean that if a SCR is implementable in strong core it is also implementable in weak core?
  - No. In general, implementable SCRs in weak and strong core are different.



- Strong core ⊆ weak core. Does this mean that if a SCR is implementable in strong core it is also implementable in weak core?
  - No. In general, implementable SCRs in weak and strong core are different.
  - SC-monotonicity does not imply and is not implied by Maskin-monotonicity.



- Strong core ⊆ weak core. Does this mean that if a SCR is implementable in strong core it is also implementable in weak core?
  - No. In general, implementable SCRs in weak and strong core are different.
  - SC-monotonicity does not imply and is not implied by Maskin-monotonicity.
- Equivalence between individual-based and non individual-based rights structures breaks down.



- Strong core ⊆ weak core. Does this mean that if a SCR is implementable in strong core it is also implementable in weak core?
  - No. In general, implementable SCRs in weak and strong core are different.
  - SC-monotonicity does not imply and is not implied by Maskin-monotonicity.
- Equivalence between individual-based and non individual-based rights structures breaks down.
  - Coalitions matter!



- Strong core ⊆ weak core. Does this mean that if a SCR is implementable in strong core it is also implementable in weak core?
  - No. In general, implementable SCRs in weak and strong core are different.
  - SC-monotonicity does not imply and is not implied by Maskin-monotonicity.
- Equivalence between individual-based and non individual-based rights structures breaks down.
  - Coalitions matter!
  - Restoring value of coalitional rights in mechanism design.



- Lombardi et al (2022).
- $M \in \mathbb{R}_+$ .



- Lombardi et al (2022).
- $M \in \mathbb{R}_+$ .
- $x = (x_1, x_2, ..., x_n) \in \mathbb{R}^n_+$ , such that  $\sum_{i \in \mathbb{N}} x_i = M$ .



- Lombardi et al (2022).
- $M \in \mathbb{R}_+$ .
- $x = (x_1, x_2, ..., x_n) \in \mathbb{R}^n_+$ , such that  $\sum_{i \in \mathbb{N}} x_i = M$ .
- Each agent *i* ∈ *N* has a weak preference relation ≿<sub>i</sub>on ℝ<sub>+</sub>, with ≻<sub>i</sub> and ~<sub>i</sub> as its asymmetric and symmetric counterparts respectively.



- Lombardi et al (2022).
- $M \in \mathbb{R}_+$ .
- $x = (x_1, x_2, ..., x_n) \in \mathbb{R}^n_+$ , such that  $\sum_{i \in \mathbb{N}} x_i = M$ .
- Each agent *i* ∈ *N* has a weak preference relation ≿<sub>i</sub>on ℝ<sub>+</sub>, with ≻<sub>i</sub> and ~<sub>i</sub> as its asymmetric and symmetric counterparts respectively.
- Set of allocations  $Z \equiv \{x \in \mathbb{R}^n_+ | \sum_{i \in N} x_i = M\}.$



- Lombardi et al (2022).
- $M \in \mathbb{R}_+$ .
- $x = (x_1, x_2, ..., x_n) \in \mathbb{R}^n_+$ , such that  $\sum_{i \in \mathbb{N}} x_i = M$ .
- Each agent *i* ∈ *N* has a weak preference relation ≿<sub>i</sub>on ℝ<sub>+</sub>, with ≻<sub>i</sub> and ~<sub>i</sub> as its asymmetric and symmetric counterparts respectively.
- Set of allocations  $Z \equiv \{x \in \mathbb{R}^n_+ | \sum_{i \in N} x_i = M\}.$
- For all  $i \in N$ ,  $\geq_i \in \mathcal{L}_i$  and  $x, y \in Z$ :

 $xR_iy$  if and only if  $x_i \gtrsim_i y_i$ .



#### The no-envy correspondence

#### No-envy correspondence

 $NE : \mathcal{R} \to 2^Z$ , such that, for all  $x \in Z$ , we have  $x \in NE(R)$  if and only if for all  $\{i, j\} \subseteq N, x_i \gtrsim_i x_j$ .

We are in general interested in the intersection of no-envy with strong (or weak) Pareto.

#### Proposition

Suppose that  $NE \cap SPO$  is non-empty. Then, it is implementable in strong core.

Environ: 00 nt

Applications 0000 Conclusion 00 Supplementary material O

# Single-plateaued preferences

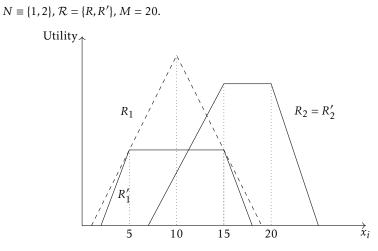


Figure: Single-plateaued preferences

Introduction	Environment	Results	Applications	Conclusion	Supplementary material
000000	00	00000	000	OO	O
		An op	en question		



• Social planner in general is ignorant about the protocol of the coalition formation process.



- Social planner in general is ignorant about the protocol of the coalition formation process.
- Strong core vs weak core.



- Social planner in general is ignorant about the protocol of the coalition formation process.
- Strong core vs weak core.
- Under what conditions can we implement a SCR that is robust to the protocol?



- Social planner in general is ignorant about the protocol of the coalition formation process.
- Strong core vs weak core.
- Under what conditions can we implement a SCR that is robust to the protocol?

**Double implementation**: for all  $R \in \mathcal{R}$ ,  $\phi(R) = h(C(\Gamma, R)) = h(SC(\Gamma, R))$ .



• Full characterization of implementation in weak and strong core.



- Full characterization of implementation in weak and strong core.
- Restoration of the value of coalitions in economic design.



- Full characterization of implementation in weak and strong core.
- Restoration of the value of coalitions in economic design.
- Importance of strong core as an equilibrium concept.



# Thanks! :-)



## Rights structures example

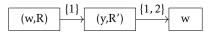


Figure: Rights structure

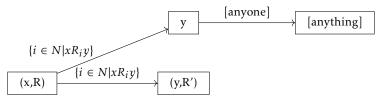


Figure: Canonical rights structure

